NUMERICAL MODELING OF HIGH-VELOCITY, PROJECTILE PENETRATING CONCRETE BLOCKS REINFORCED BY TEFLON SHEETS

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ABSTRACT

Recently, the concern about protecting people and structures has increased due to the increasing number of terrorist attacks. This paper presents a numerical simulation of plain concrete blocks with an unconfined compressive strength of 35 MPA, reinforced by Teflon sheets and subjected to ballistic impact by a high-velocity rigid projectile (960 m/s). The reinforcement sheets are modeled with different thicknesses and located at different depths from the face of the concrete target. The Teflon material was chosen due to its high impact strength over a wide range of temperatures. A validation model was conducted and results showed a good agreement with previous experimental results. The investigation presents the development of a finite element accurate model using AUTODYN 3D. The Lagrangian formulation numerical technique is used to model both the projectile and the concrete target. The main findings showed an enhancement in the penetration resistance of concrete target when reinforced by Teflon sheets compared to the concrete resistance without reinforcement, where the projectile depth of penetration was reduced by 64.8% and the full damage depth of the concrete target was also reduced by 58%, which demonstrates the great performance of the chosen reinforcement in the shock wave propagation.

Keywords: ballistic, impact, concrete, Teflon, projectile, numerical modeling.

1 INTRODUCTION

As one of the most important and effective construction materials, concrete may be subjected to extreme dynamic loads such as blast and impact loading causing penetration and perforation and leading to failure of the structure; this impact may be caused by terrorist attacks or high-velocity fragments resulted from accidental explosions.

In the last decade, many empirical and numerical models and experimental studies were conducted to analyze the behavior of normal reinforced concrete subjected to impact loading with different range of velocity.

Experimental studies of plain and reinforced concrete targets subjected to impact loading were of great interest to researches such as Rajput et al. [1] who conducted penetration tests on different thicknesses of plain and reinforced concrete plates to study the influence of impact of hard steel projectile on their ballistic performance; while Iqbal et al. [2] compared the ballistic limit and the damaged area of plain and reinforced concrete when subjected to normal impact of hardened steel projectiles.

On the other hand, many numerical models were conducted to study and analyze the penetration and perforation of different elements of normal reinforced concrete, such as Smith and Cusatis [3] who studied the impact of a projectile on regular strength concrete (RSC) and high-strength concrete (HSC) using the Lattice Discrete Particle Model (LDPM). Jiricek and Foglar [4] simulated the impact of regular and sub-caliber projectile on military bunkers (concrete blocks) using Autodyne 3D. Another numerical simulation was conducted using Autodyne by Tawadrous et al. [5]; they modeled numerically the penetration of a high velocity projectile to concrete blocks reinforced by ceramic.



Some researches combined simulations and experiments to compare the results and validate the proposed numerical models; such as Almusallam et al. [6] who compared the effect of CFRP strengthening on the response of reinforced concrete slabs when modeled experimentally and numerically using LS-DYNA; the analysis was conducted for the impact of hemispherical steel projectile with varying velocity and the slabs. Pavlovic and Fragassa [7] evaluated the resistance level of reinforced concrete barriers subjected to ballistic impact; the study was done with explicit Finite Element (FE) simulations and the results were compared to experimentally and numerically concrete by different number of layers of woven wire steel mesh experimentally and numerically using a steel blunt-nose projectile with a diameter of 23 mm with striking velocity about 980 m/s; they found an overall reduction in penetration depth and damage of target when using wire meshes as a reinforcement.

This paper aims to enhance the penetration resistance of plain concrete blocks to high velocity projectile impact by using tetrafluoroethylene polymer sheets (PTFE) known as Teflon as reinforcement for plain concrete. Teflon was chosen due to its excellent impact strength over a wide range of temperatures according to the Teflon handbook published by DuPont [9].

2 METHOD AND MATERIALS

Impact is defined as a high force or shock applied over a very short time from a body to another one and inducing significant local contact deformation. From the perspective of conservation of energy, the kinetic energy of the impacting body will be partially converted to strain energy in the target and partly dissipated through friction and local plastic deformation, and the strain energy is radiated away as stress waves.

The mechanism of penetration differs from one material to another; this section will discuss the penetration mechanism in concrete, metals, ceramics, polymers and composites. During ballistic impact, a pressure wave is induced and expands radially through the concrete target, leading to interfering stress wave that results in rapid change in multiaxial stress states and strain rates of the target. Material local failure can occur in four main stages [10] as shown in Fig. 1:

- 1. Penetration: the projectile tunneling into the target by a length called the penetration depth, formation of a cone-like crack under the projectile.
- 2. Spalling and scabbing: the target material ejecting from the front and rare faces.
- 3. Perforation: the projectile passing completely through the target with or without a residual velocity.
- 4. Recovery phase: it is the period during which the crater recovers or contracts slightly.

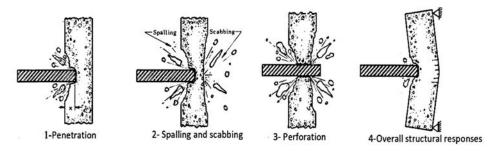


Figure 1: Projectile impact main stages [10].

The penetration of polymer plates occurs by elastic dishing, petalling, cone cracking, and plugging, the projectile, pushing a cylinder of material ahead, reaches the rear surface and perforation occurs. The mechanism of failure can be explained by tensile failure, increase and cohesion of planar cracks, formation of voids, and shear instabilities [11].

2.1 Numerical analysis

With the increasing power and speed of numerical FE codes and explicit dynamic solvers, it is possible to use numerical analysis and computer simulation to model any ballistic impact case. The hydrocode Autodyne is one of the most efficient codes used to simulate ballistic impact problems and it is used in this paper to model the depth of penetration and the damage in concrete targets. The Lagrangian formulation was chosen to simulate both the projectile and the concrete target.

In Lagrangian formulation, each grid point has different material coordinates and elements are created by connecting the grid points. The element or the mesh deforms with the body, i.e. both the grid nodes and the material points change position as the body deforms but the position of the material points relative to the grid nodes remains fixed as shown in Fig. 2. The grid points are forced to move with the element when the body is subjected to deformation.

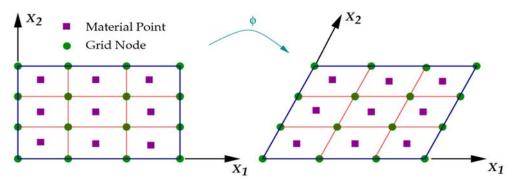
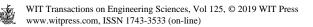


Figure 2: Lagrangian mesh before and after body deformation.

The main difficulty of Lagrangian mesh is the severe distortion that usually occurs causing stability problems and breaking the discretization. Deformations also cause the mesh to become ill-conditioned and result in decreasing stable time steps and mesh entanglement. This problem can be solved by defining an erosion mechanism that can remove the distorted elements to allow the calculation to continue. The main advantages of this numerical formulation are the fast solution due to fewer computations per cycle; the high accuracy in describing the material interfaces; the automatic satisfaction of the mass conservation; the ability to apply various boundary conditions; and the availability to handle damage and plasticity.

2.2 Geometry and mesh description

The dimensions of the simulated concrete block target are 500 mm \times 500 mm \times 400 mm, the concrete block is symmetric with respect to X and Y axis (X = 0 and Y = 0); to take advantage of the symmetry condition and to reduce the computational domain, the block is represented



by its quarter (250 mm \times 250 mm \times 400 mm) as shown in Fig. 3. The concrete region local to the projectile (100 mm \times 100 mm) which experiences large deformations is defined by a fine mesh of (2.5 mm \times 2.5 mm \times 3 mm) in *i*, *j* and *k* directions and a grade zoning is defined for the region far from the projectile in *i* and *j* directions, where little or no deformations occur, to reduce the computational time. The projectile geometry has a diameter of 23 mm and a length of 64 mm; it is modeled as a ¹/₄ cylinder; the geometry and mesh description of projectile are shown in Fig. 4. The model boundary condition is fixed from the side and the projectile has a velocity of 960 m/s in Z-direction.

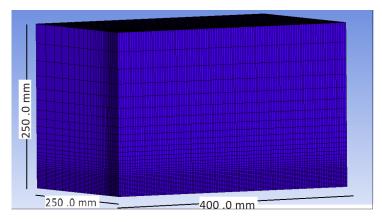


Figure 3: Concrete block geometry and meshing.

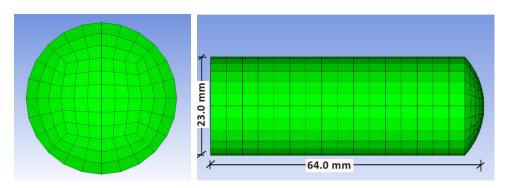
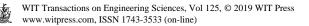


Figure 4: Projectile geometry and meshing.

2.3 Material description

The material models are chosen from AUTODYN library to simulate the used materials as following: STEEL4340 is used to simulate the projectile, while CONC-35MPA is used to simulate the plain concrete of unconfined compressive strength 35 MPA; and TEFLON for the polymer PTFE (known as Teflon). The details of the materials description are shown in Tables 1 to 3 where the Equation of State, the strength model and the failure model for each material are presented as well as the erosion model if it existed.



Parameter	Value	Parameter	Value
Equation of state	Johnson Cook	Hardening constant (KPa)	1.79E+07
Reference density (gm/cm ³)	7.83	Hardening exponent	0.26
Bulk modulus (KPa)	1.67E+08	Strain rate constant	0.014
Reference temperature (K)	300	Thermal-softening exponent	1.03
Specific heat (C.V.) (j/kg K)	477	Melting temperature (k)	1793
Strength model	Johnson Cook	Ref. strain rate (/s)	1.00
Shear modulus (KPa)	7.98E+07	Erosion model	Geometric strain
Yield Stress (KPa)	1.73E+06	erosion strain	3.50

Table 1: Material constants for steel (STEEL4340).

Table 2: Material constants for concrete (CONC-35MPA).

Parameter	Value	Parameter	Value
Equation of state	P-alpha	Failure surface parameter A	2
Reference density (gm/cm ³)	2.7	Failure surface exponent N	0.7
Porous density (gm/cm ³)	2.350	Tens./comp. meridian ratio	0.6805
Porous sound speed (m/s)	2.92E+03	Brittle to ductile transit	0.0105
Initial compaction pressure (KPa)	2.33E+04	G (elas.)/G (elasplas.)	2
Solid compaction pressure (KPa)	6.00E+06	Compaction curve	Standard
Compaction exponent n	3.00	Elastic strength/ft	0.7
Solid EOS	Polynomial	Elastic strength/fc	0.53
Bulk modulus A1 (KPa)	3.53E+07	Use cap on elastic surface	1
Parameter A2 (KPa)	3.96E+07	Fractured strength constant	1.50
Parameter A3 (KPa)	9.04E+06	Fractured strength exponent	0.61
Parameter B0	1.22	Compressive strain rate	0.032
Parameter B1	1.22	Tensile strain rate exponent	0.025
Parameter T1 (KPa)	3.53E+07	Max. fracture strength ratio	1.00E+20
Parameter T2 (KPa)	0.00	Failure model	RHT concrete
Reference temperature (K)	300.00	Damage constant D1	0.04
Specific Heat (C.V.) (j/kg K)	654.00	Damage exponent D2	1.00
Strength Model	RHT concrete	Min. strain to failure	0.01
Shear modulus (KPa)	1.67E+07	Residual shear modulus frac.	0.13
Compressive strength fc (KPa)	3.50E+04	Tensile failure model	Hydro tens.
Tensile strength ft/fc	0.088	Erosion model	Geometric strain
Shear strength fs/fc	0.18	Erosion strain	1.045



Parameter	Value	Parameter	Value
Equation of state	Shock	Strength model	von Mises
Reference density (gm/cm ³)	2.16	Shear modulus (KPa)	2.33E+06
Gruneisen coefficient	0.9	Yield Stress (KPa)	5.00E+04
Parameter C1 (m/s)	1.34E+03	Failure model	Hydro (Pmin)
Parameter S1	1.93	Hydro tensile limit	-1.00E+06
Reference temperature (K)	0	Reheal	yes
Specific heat (j/kg K)	0	Crack softening	no

Table 3:	Material	constants	for teflon	(TEFLON).
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3 NUMERICAL AND VALIDATION MODELS

An experimental study was conducted by Mohamed et al. [12] on a concrete block with the same dimensions (500 mm x 500 mm x 400 mm) having a compressive strength of 35 MPa and a density of 2,350 mg/cm³; the block was subjected to a similar projectile of diameter 23 mm and having a striking velocity about 970 m/s as shown in Fig. 5. The concrete target was supported by the steel frame along its perimeter to prevent movement in both directions, then it was fired by the projectile. Fig. 6 shows the concrete block before and after impact. The recorded depth of penetration was 400 mm and the front and rear faces were fully damaged.

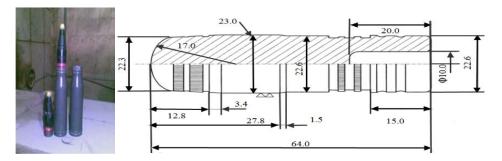


Figure 5: Dimensions of the projectile.



Figure 6: Concrete block before and after impact.

The first model in this paper is used for numerical validation. The model that was simulated using the dimensions and properties of the experimental model, recorded a depth of penetration of 390 mm when it was subjected to a 23 mm projectile with a velocity of 960 m/s as shown in Fig. 7; this shows a good agreement with the experiment result of the plain concrete block subjected to the same projectile. Fig. 8 shows the predicted damage contour of concrete target, it is obvious that the block was fully damaged.

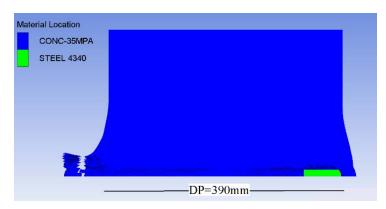


Figure 7: Depth of penetration for target with no reinforcement = 390 mm.

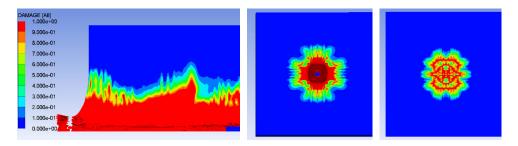


Figure 8: Damage contour for concrete without reinforcement: side section, front face and rear face.

The concrete target models simulated in this paper are reinforced by the chosen material (Teflon) with different thickness and at different locations. Five different thinness and locations are suggested to enhance the impact behavior of concrete block and increase its resistance to penetration of high velocity projectile. The first two models consist of two layers of 9 mm each and the other three models consist of one layer of 18 mm. Fig. 9(a) to 9(e) show the layers location and thickness of models 1 to 5 respectively.

4 RESULTS AND DISCUSSION

The results of the simulation are captured and presented in this section in terms of the projectile depth of penetration as well as the degree of concrete target damage.

The interaction between the concrete target models with Teflon layers reinforcements and the projectile was captured and represented in this section. The results show that the



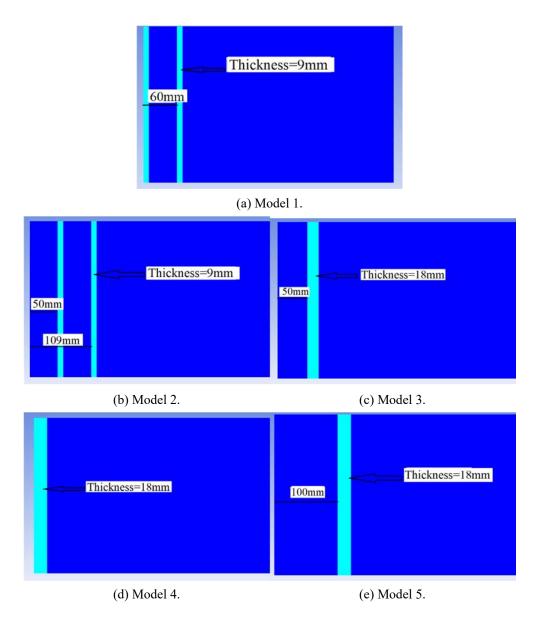
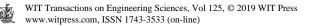


Figure 9: Teflon sheets location and thickness.

minimum depth of DP occurred in model 1, and also the minimum depth of TD. The Teflon reinforcement in model 1 is divided into two layers situated at distances 0 and 60 mm from the face of concrete target; a DP of 137 mm was recorded which means that the resistance of concrete is increased by about 65% compared to its resistance without the Teflon reinforcement. For model 2, the Teflon is also divided into two layers but situated deeper at distances 50 and 109 mm; the DP and TD recorded for this model show also an enhancement



in concrete resistance but they are higher than model 1, which means that, when the reinforcement is located at lower depth, the resistance to ballistic impact is greater than when it is located at greater depth. For the models 3, 4 and 5, only one Teflon layer of thickness 18 mm is used as a reinforcement at distances 0, 50 and 100 mm respectively. The lowest DP and TD are recorded for model 3, while model 4 recorded higher DP and TD than model 3, and model 5 recorded the highest values. It can be concluded from these results also that the deeper the Teflon sheets are located in the concrete target, the higher values for DP and TD are obtained. Comparing the results of model 1 and 3, it is obvious that projectile DP in model 1 is lower; which means that when dividing the Teflon reinforcement into two layers of the same total thickness, we decrease the DP by about 14% but the total damage TD remains the same.

Table 4 summarizes the results of the five models concerning the depth of penetration of the projectile into the concrete target (DP) and the percentage of decrease of the DP with respect to the concrete model without reinforcement as well as the depth of the area of concrete subjected to total damage (TD). Contour plots of deformation and material damage are shown in Fig. 10(a) to 10(j).

Model #	Projectile depth of penetration (DP)	% of reduction in DP	Depth of concrete total damage (TD)	% of reduction in TD
Model 1	137 mm	64.8%	168 mm	58.0%
Model 2	164 mm	57.9%	224 mm	44.0%
Model 3	156 mm	60.0%	168 mm	58.0%
Model 4	164 mm	57.9%	189 mm	52.7%
Model 5	183 mm	53.1%	210 mm	47.5%

Table 4: The results of simulated models.

5 CONCLUSION

This paper presents an investigation of the ballistic performance of concrete blocks reinforced by Teflon sheets at different locations and with different thicknesses and subjected to high-velocity rigid projectile (960 m/s). The finite element models were numerically simulated using the hydrocode Autodyne 3D, and some results were compared to previous experimental work found in literature. The effect of the used material on the penetration depth of projectile and the resulted damage of concrete are presented and explained: the projectile depth of penetration can be decreased from 390 mm to 137 mm with an improvement of 64.8%, and the full damage depth is decreased from 400 mm to 168 mm with an improvement of 58%, which means a very good enhancement in penetration resistance and the degree of damage of concrete target.

From the previous analysis, we can conclude that the usage of tetrafluoroethylene polymer sheets, known as Teflon, as reinforcement for plain concrete blocks can be considered as a successful anti-penetration composite structure.



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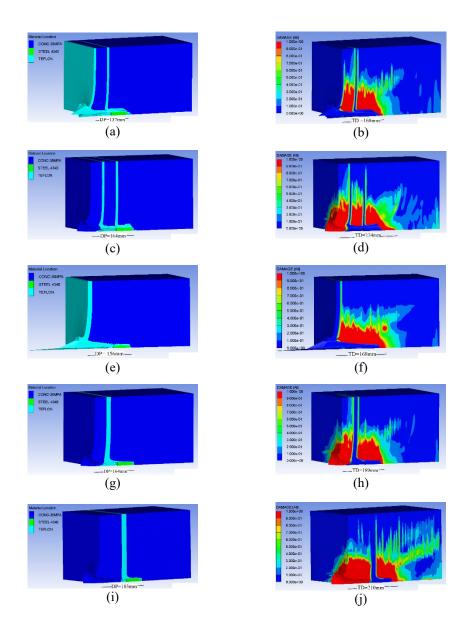


Figure 10: Impact simulation results. (a) Model 1 depth of penetration of projectile, DP = 137 mm; (b) Model 1 damage contours of concrete, TD = 168 mm; (c) Model 2 depth of penetration of projectile, DP = 164 mm; (d) Model 2 damage contours of concrete, TD = 224 mm; (e) Model 3 depth of penetration of projectile, DP = 156 mm; (f) Model 3 damage contours of concrete, TD = 168 mm; (g) Model 4 depth of penetration of projectile, DP = 164 mm; (h) Model 4 damage contours of concrete, TD = 189 mm; (i) Model 5 depth of penetration of projectile, DP = 183 mm; and (j) Model 5 damage contours of concrete, TD = 210 mm.



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